

Milstein scheme for SQG under LU

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in collaboration with
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The logo for Inria, featuring the word "Inria" in a stylized, cursive font. The letters are colored with a gradient from red to orange.

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SQG system under location uncertainty

LU framework: based on the following decomposition of the Lagrangian velocity in two components

$$d\mathbf{X}_t = \mathbf{u}(\mathbf{X}_t, t)dt + \sigma(\mathbf{X}_t, t)d\mathbf{B}_t$$

one can compute the **stochastic transport operator**:

$$\mathbb{D}_t b := d_t b + \mathbf{v}^* \cdot \nabla b dt + \sigma d\mathbf{B}_t \cdot \nabla b - \frac{1}{2} \nabla \cdot (a \nabla b) dt,$$

where

$$\mathbf{v}^* = \mathbf{u} - \frac{1}{2} \nabla \cdot a - \sigma(\nabla \cdot \sigma)$$

Therefore, the surface quasi geostrophic system under location uncertainty is:

$$\begin{cases} \mathbb{D}_t b = 0, \\ b = N(-\Delta)^{1/2} \psi, \\ \mathbf{u} = \nabla^\perp \psi, \end{cases}$$

Towards the Milstein scheme

The main equation is:

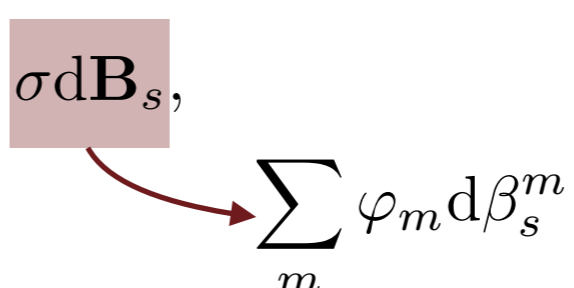
$$b_t = b_{t_0} + \int_{t_0}^t \frac{1}{2} \nabla \cdot (a \nabla b) - \mathbf{v}^* \cdot \nabla b \, ds - \int_{t_0}^t \nabla b \cdot \sigma \, d\mathbf{B}_s,$$

We model the noise by decomposing $\sigma d\mathbf{B}_t$ onto a basis, with two different approaches:

- POD approach $\sigma d\mathbf{B}_t \simeq \sum_{m=1}^N \varphi_m(\mathbf{x}) d\beta_t^m$
- SVD approach $\sigma d\mathbf{B}_t \simeq \sum_{m=1}^N \varphi_m(b_t) d\beta_t^m$

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$$\sum_m \varphi_m \, d\beta_s^m,$$

We define the following functions:

$$f(b_t, t) = \frac{1}{2} \nabla \cdot (a \nabla b) - \mathbf{v}^* \cdot \nabla b \quad g^m(b_t, t) = \nabla b \cdot \varphi_m$$

We can apply Itô formula for f and g^m , obtaining:

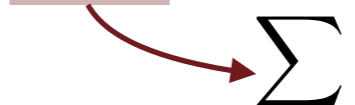
$$f(b_t, t) = f(b_{t_0}, t_0) + \int_{t_0}^t \frac{\partial f}{\partial s}(b_s, s) \, ds + \int_{t_0}^t \frac{\partial f}{\partial b}(b_s, s) \, db_s + \frac{1}{2} \int_{t_0}^t \frac{\partial^2 f}{\partial b^2}(b_s, s) \, d\langle b, b \rangle_s$$

$$g^m(b_t, t) = g^m(b_{t_0}, t_0) + \int_{t_0}^t \frac{\partial g^m}{\partial s}(b_s, s) \, ds + \int_{t_0}^t \frac{\partial g^m}{\partial b}(b_s, s) \, db_s + \frac{1}{2} \int_{t_0}^t \frac{\partial^2 g^m}{\partial b^2}(b_s, s) \, d\langle b, b \rangle_s$$

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Towards the Milstein scheme

The bracket is:

$$\langle b, b \rangle_t = \left\langle \int_{t_0}^{\cdot} \sum_m g^m(b_s, s) d\beta_s^m, \int_{t_0}^{\cdot} \sum_k g^k(b_\tau, \tau) d\beta_\tau^k \right\rangle_t = \int_{t_0}^t \left(\sum_m g^m(b_s, s) \right)^2 ds$$

As for the derivatives, we suppose to be in either one of the following cases:

- a and σ (therefore φ^m) do not depend on b and $\nabla \cdot \mathbf{v}^* = 0$
- a and σ depend on b and $\nabla \cdot \mathbf{v}^* = \nabla \cdot \nabla \cdot a = \nabla \cdot \sigma = 0$

Then we have:

$$\frac{\partial f}{\partial b}(\bar{b})b = f(b) \qquad \frac{\partial g^m}{\partial b}(\bar{b})b = g^m(b)$$

Milstein scheme

By replacing everything in the Itô formulas and then into the main equation, one finds:

$$b_t = b_{t_0} + f(b_{t_0})\Delta t - \sum_m g^m(b_{t_0})\Delta\beta^m + \int_{t_0}^t \int_{t_0}^s \sum_{m,k} g^m(g^k(b_\tau))d\beta_\tau^k d\beta_s^m \quad (1)$$

Euler-Maruyama

We define the following quantities:

$$G^{m,k} := g^m(g^k(b_{t_0})) \quad I^{m,k} := \int_{t_0}^t \int_{t_0}^s d\beta_\tau^k d\beta_s^m$$

Then the double integral in (1) can be approximated with:

$$\sum_{m,k} G^{m,k} I^{m,k} = \sum_{m,k} G^{m,k} \frac{I^{m,k} + I^{k,m}}{2} + G^{m,k} \frac{I^{m,k} - I^{k,m}}{2}$$

weak approximation
recursive (conditional)
approximation
neglected

Lévy area,
which can
be simulated

Remark: if G is symmetric (i.e. $G^{m,k} = G^{k,m}$), then the Lévy area is not necessary:

$$\sum_{m,k} G^{m,k} I^{m,k} = \frac{1}{2} \sum_{m,k} G^{m,k} I^{m,k} + G^{k,m} I^{k,m} = \sum_{m,k} G^{m,k} \frac{I^{m,k} + I^{k,m}}{2}$$

Numerical results

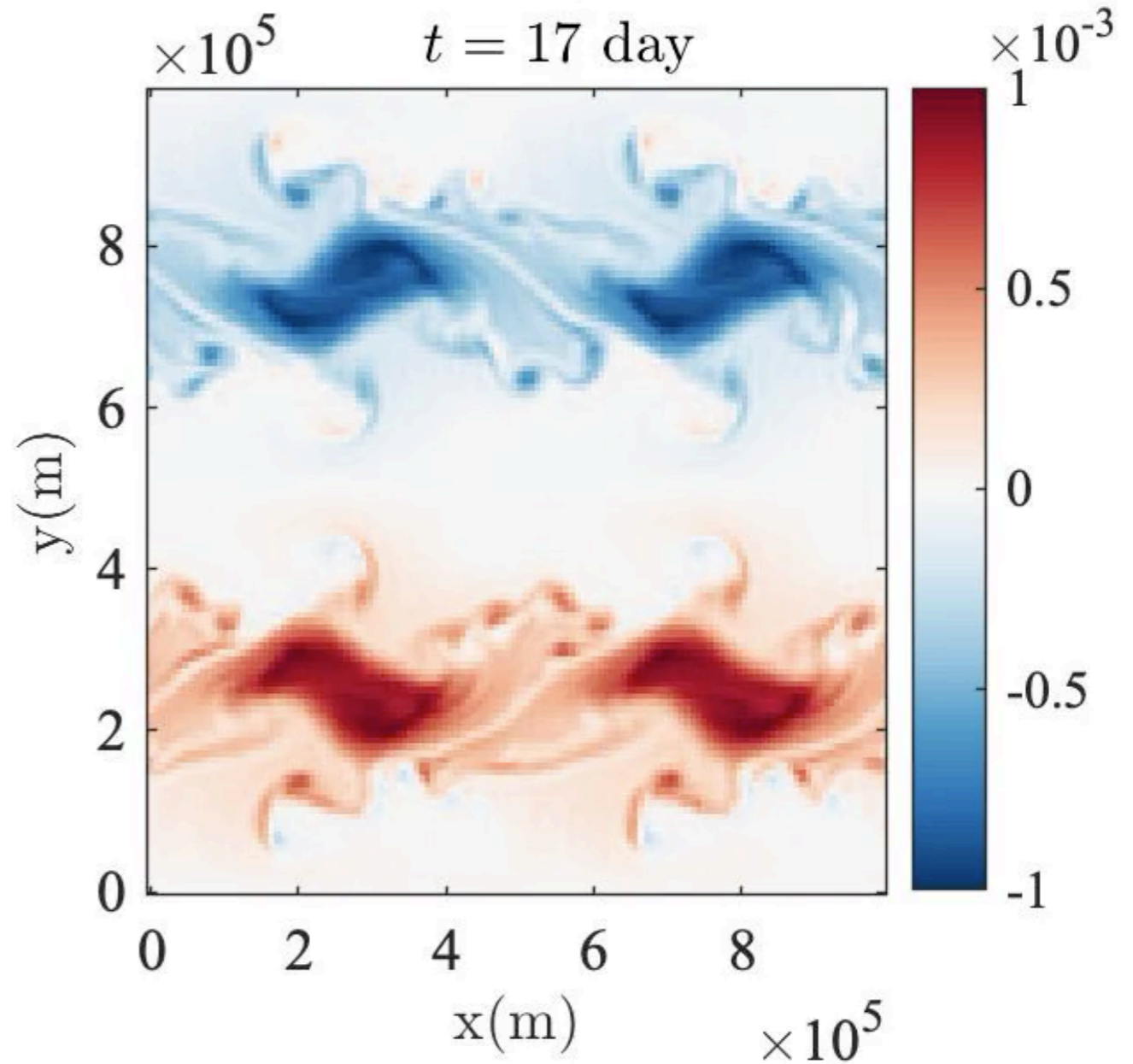
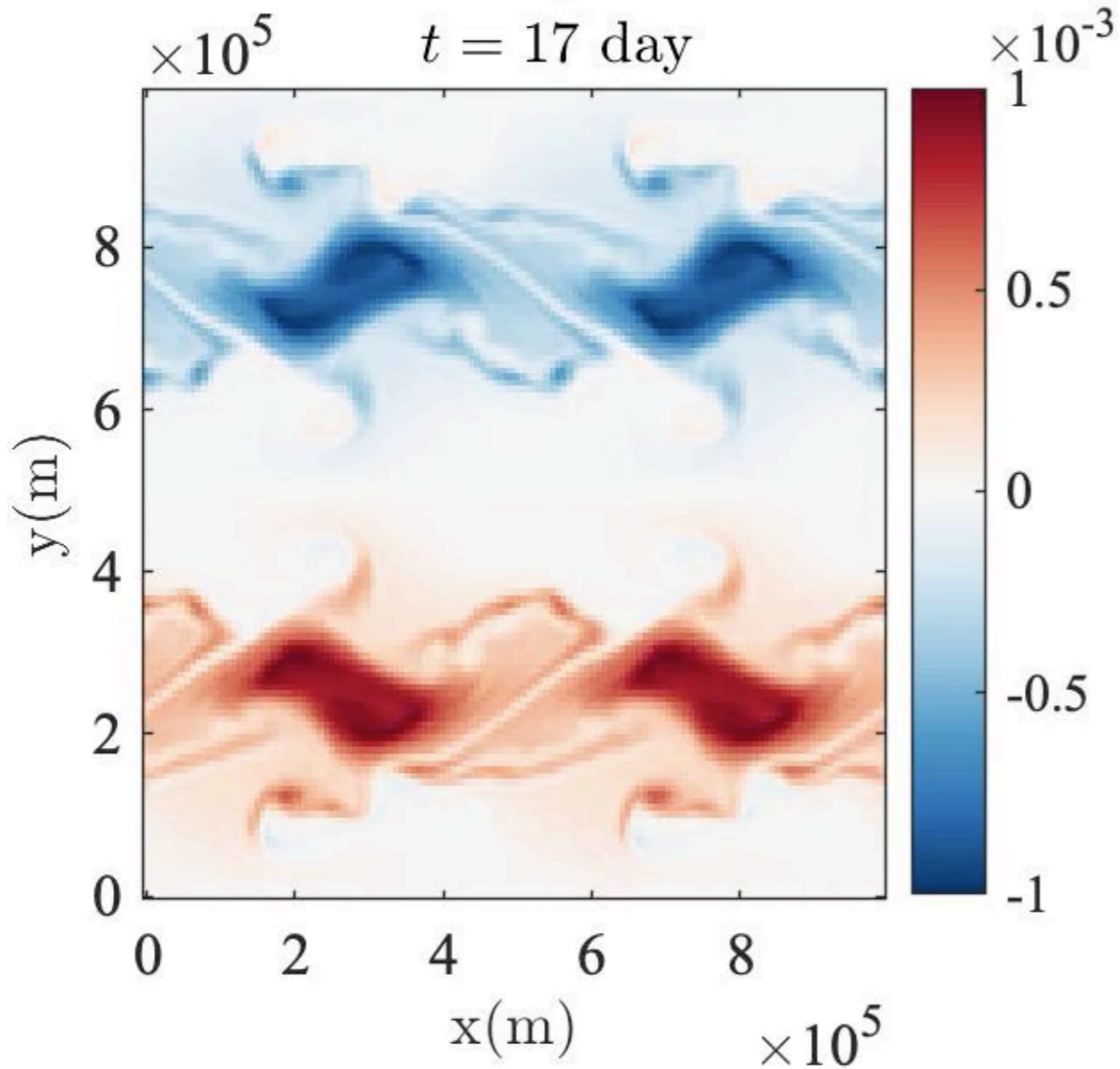
POD noise

Euler Maruyama

Milstein - weak

One realization
 $t = 17$ day

One realization
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Numerical results

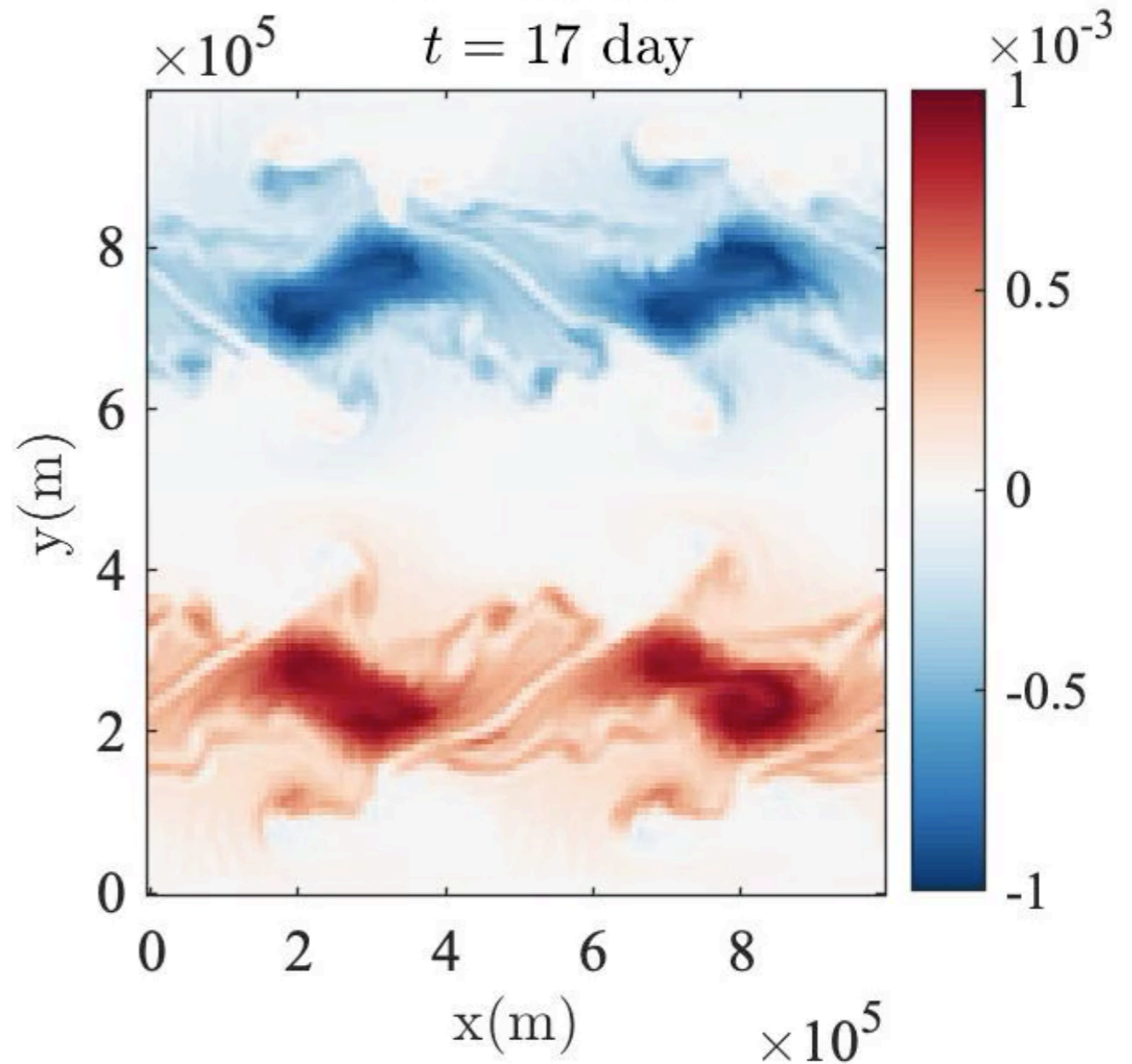
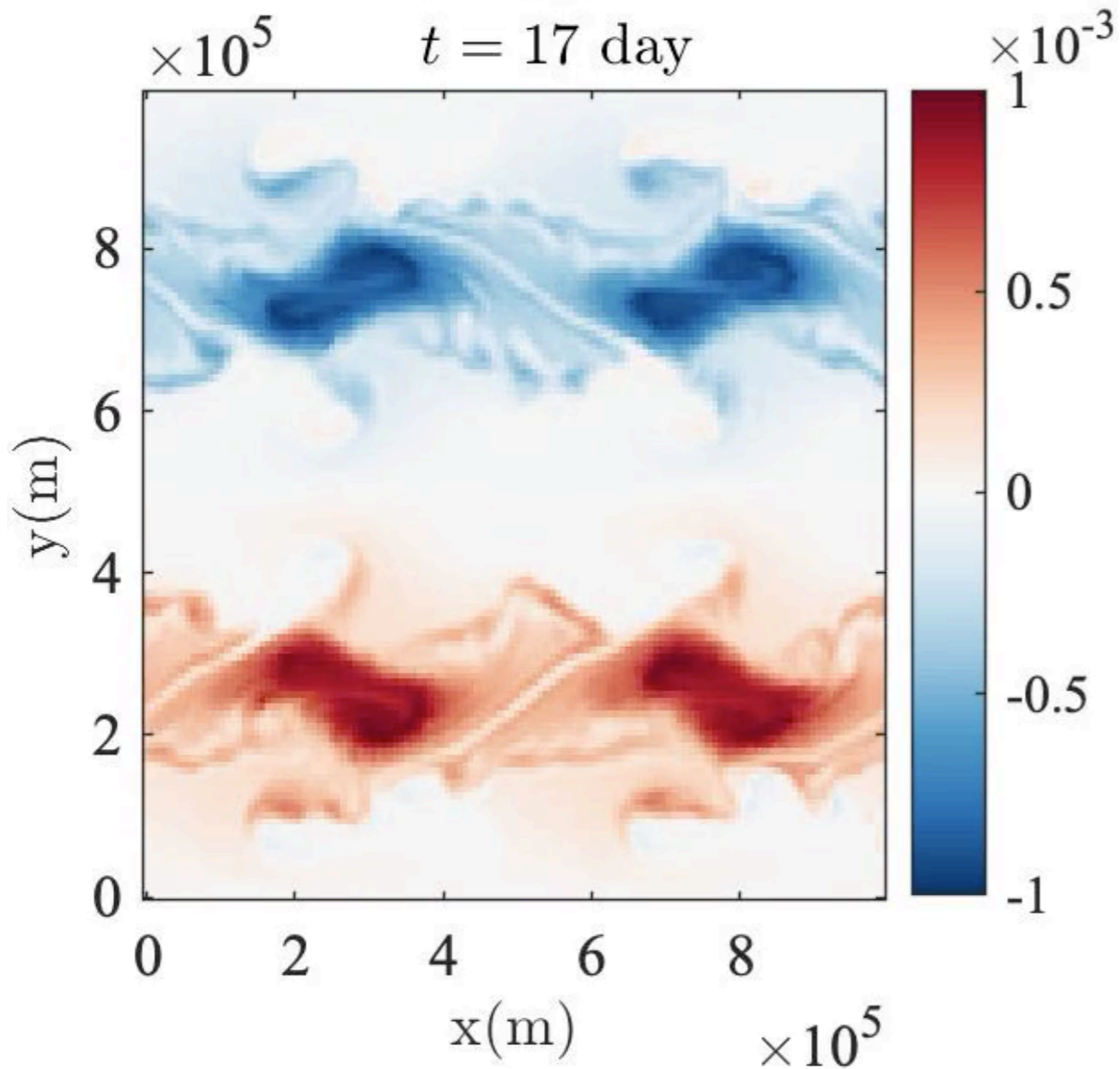
SVD noise

Euler Maruyama

Milstein - weak

One realization
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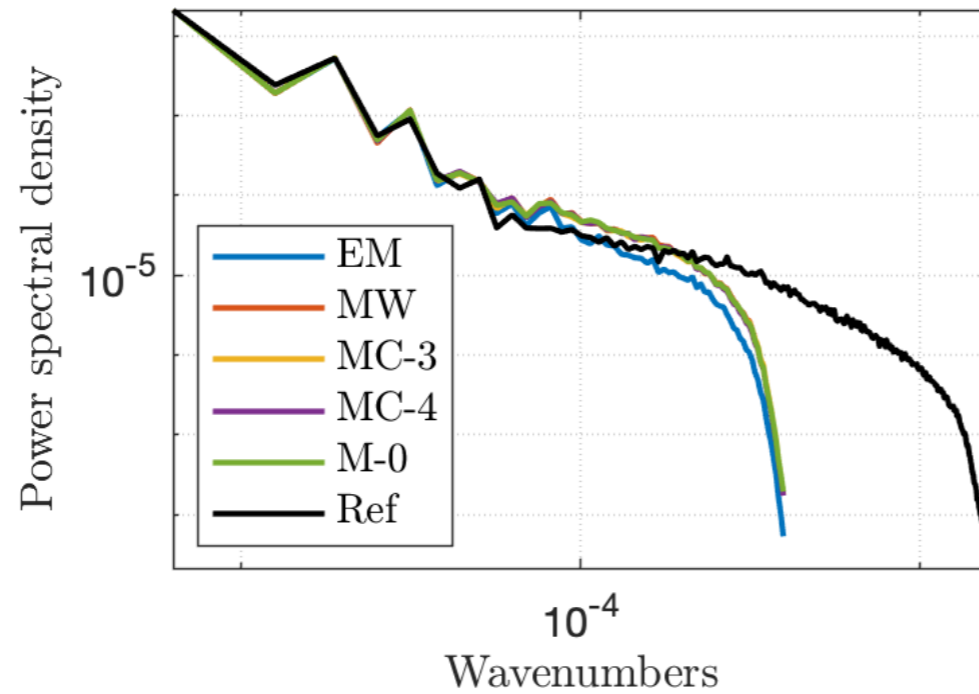
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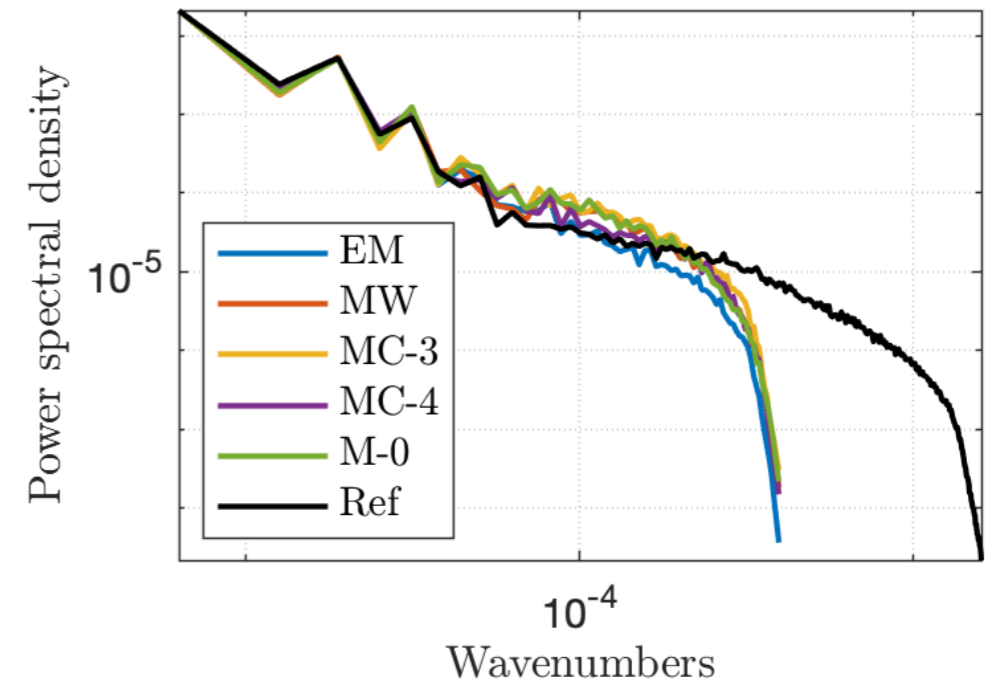
Numerical results

POD noise

Mean spectrum of buoyancy at day = 30

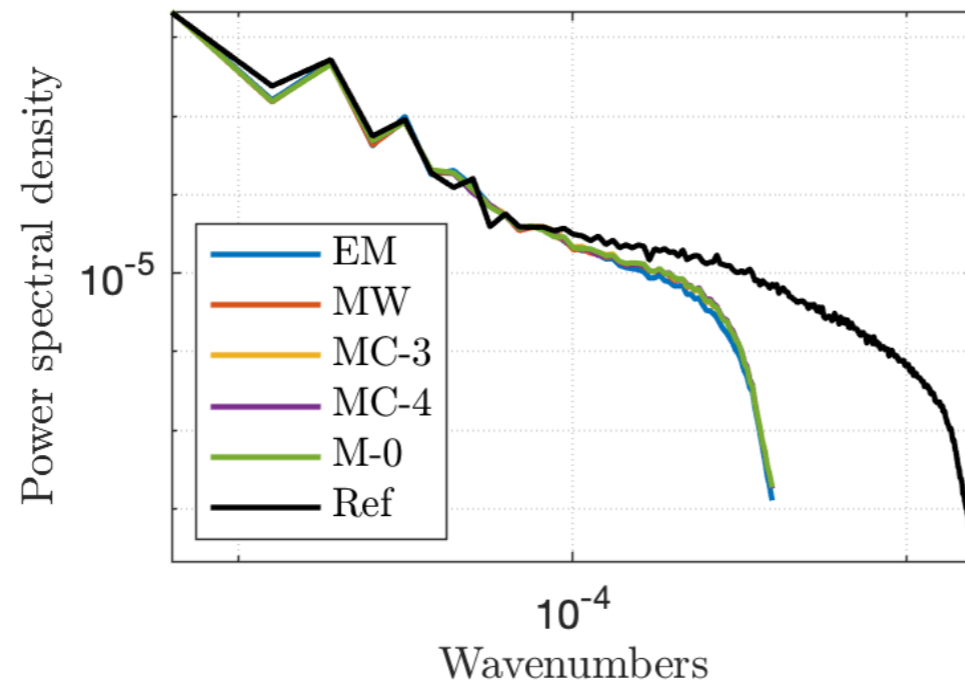


Spectrum of buoyancy at day = 30

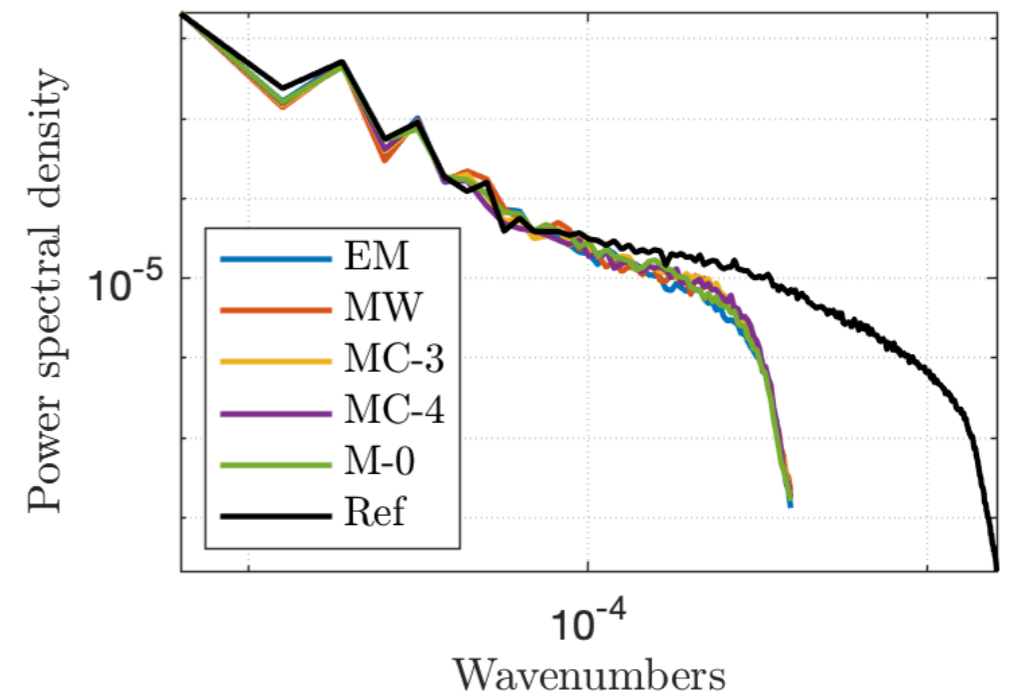


SVD noise

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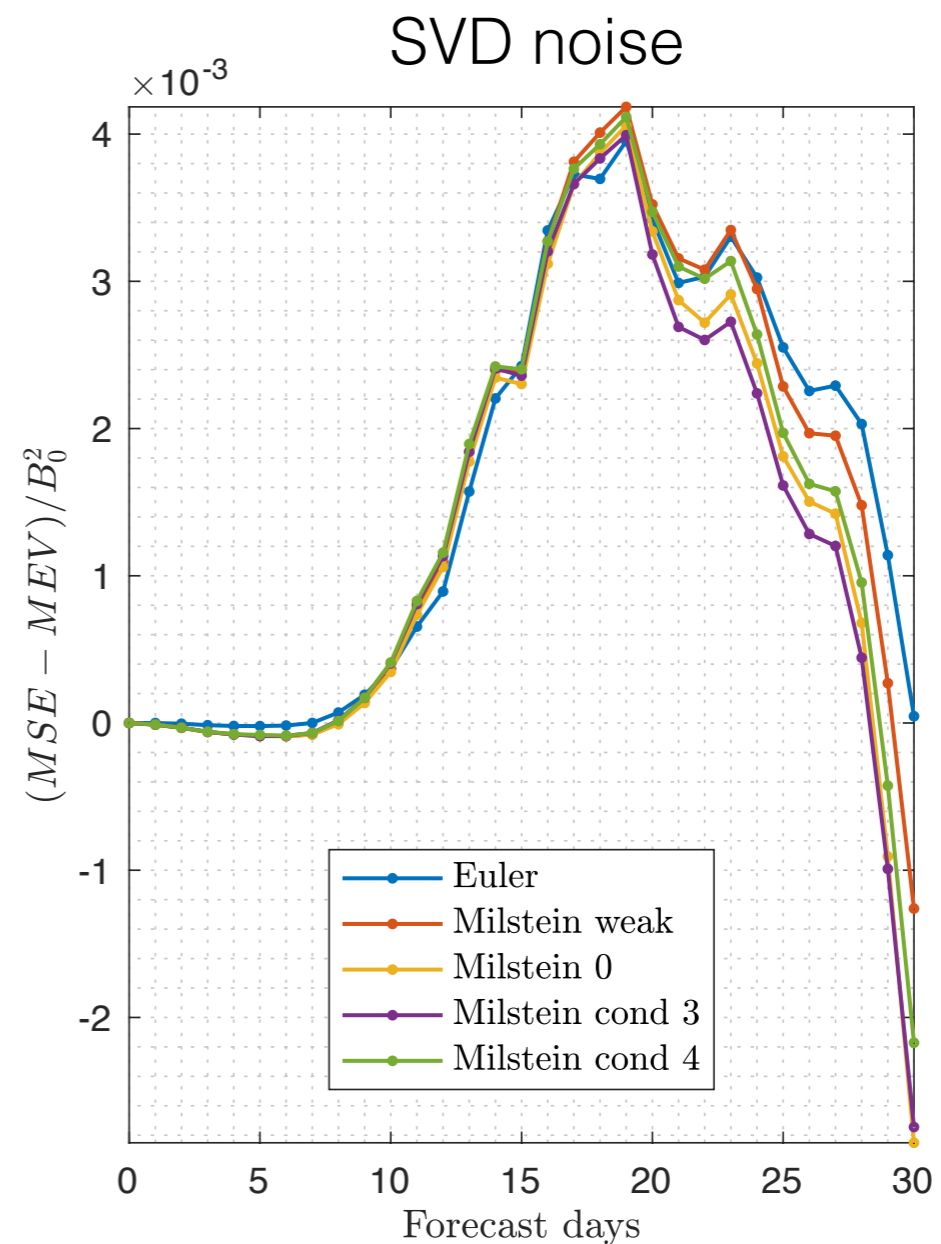
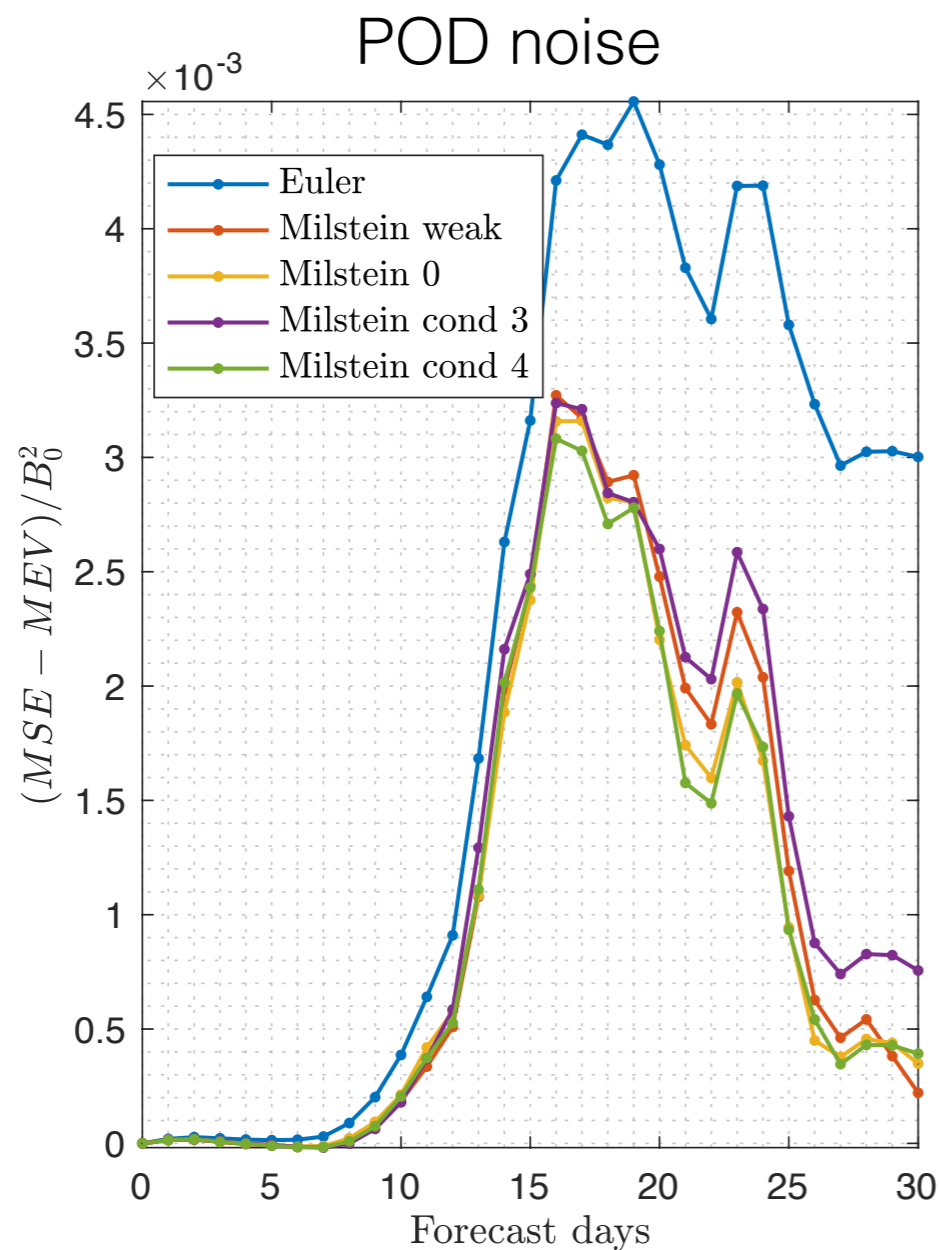
Spectrum of buoyancy at day = 30



Numerical results

A necessary condition for ensemble reliability is that the mean squared error (MSE) of the ensemble mean forecast is close to the mean ensemble variance:

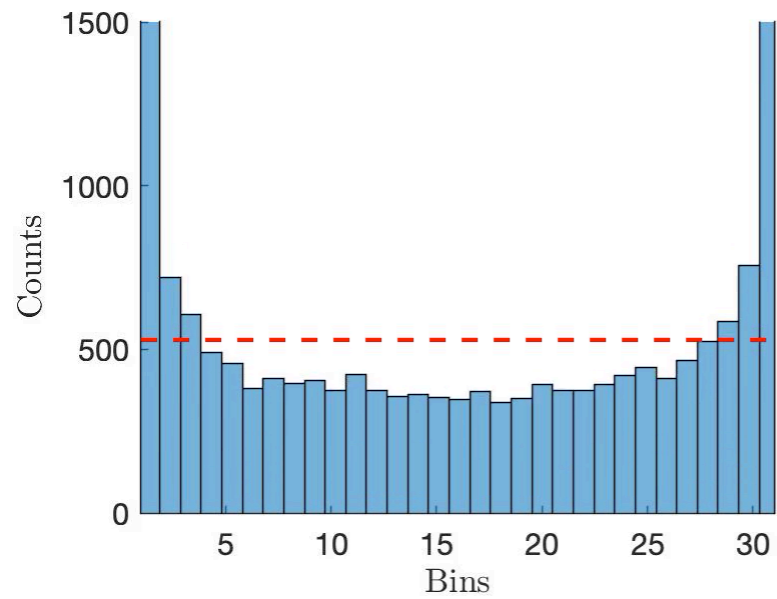
$$\text{MSE} = \sum_{n=1}^N \left(\hat{\mathbb{E}}[b_n] - b_n^{\text{obs}} \right)^2 \simeq C \left(\frac{1}{N} \sum_{n=1}^N \hat{\text{Var}}[b_n] \right) = \text{MEV}$$



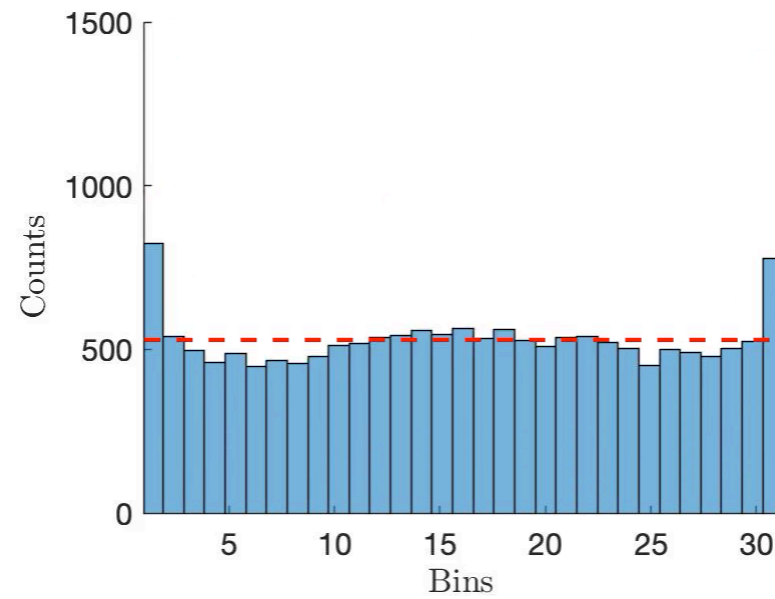
Numerical results

POD noise

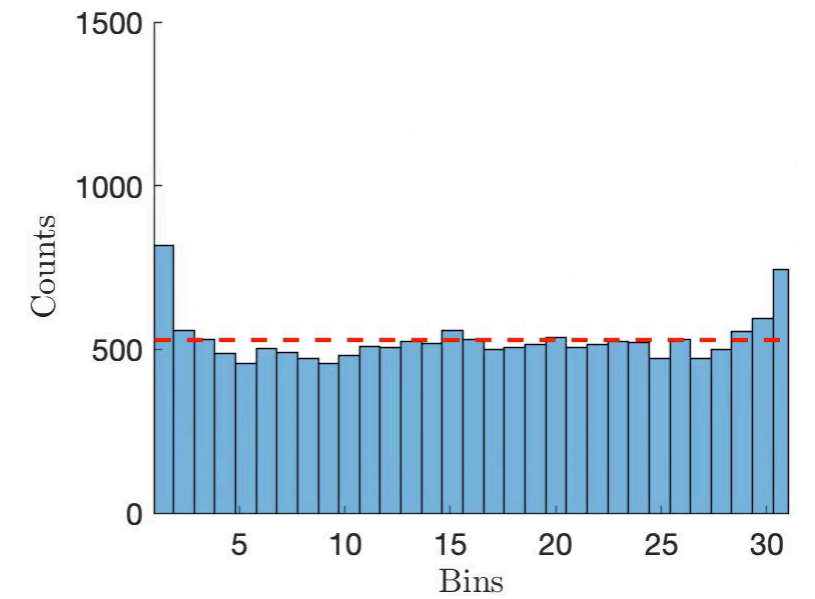
Euler Maruyama



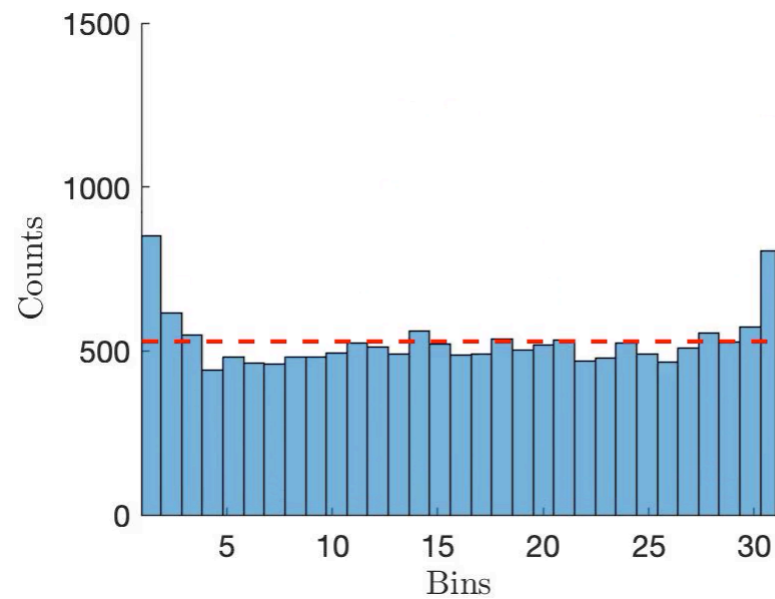
Milstein weak



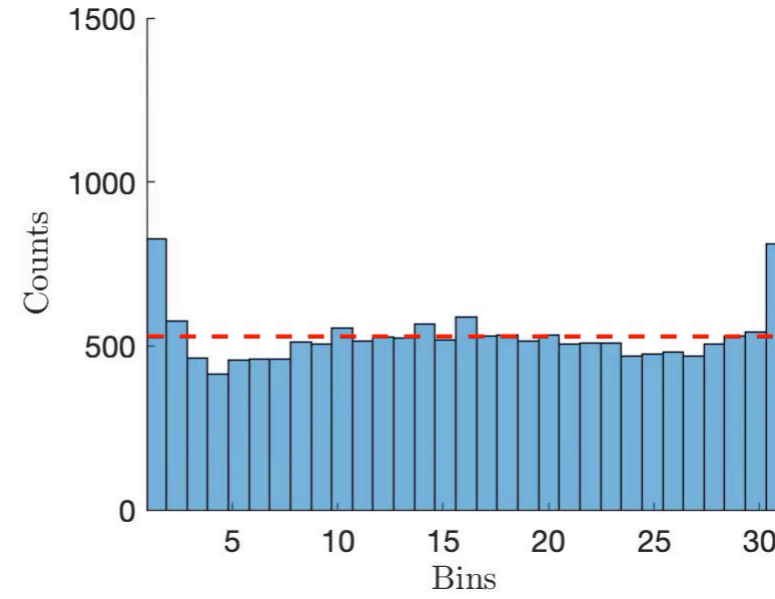
Milstein 0



Conditional 3



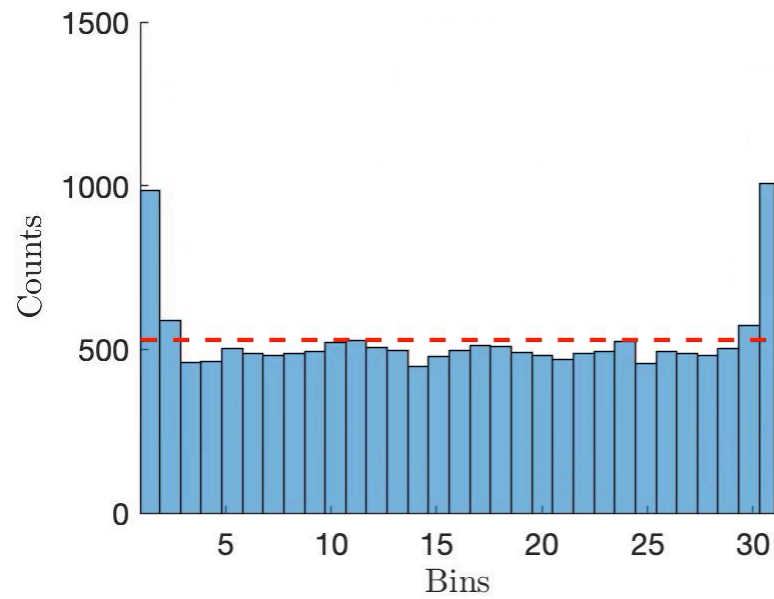
Conditional 4



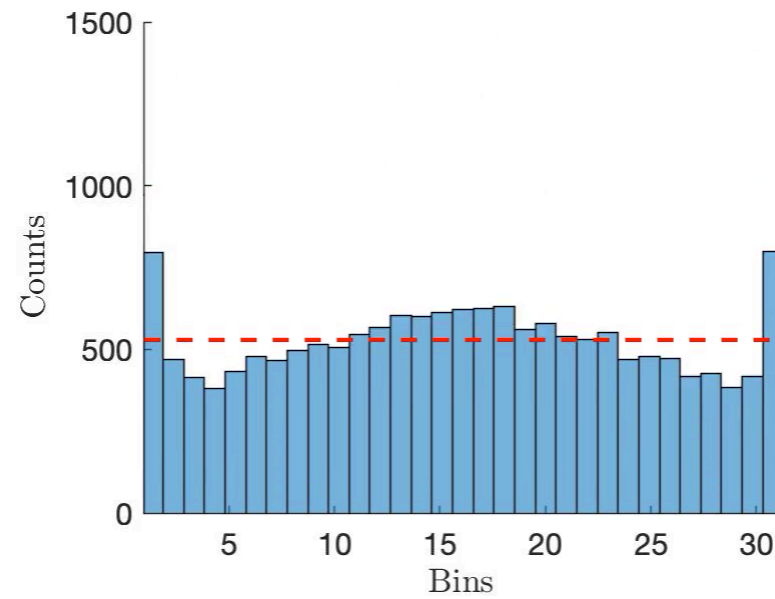
Numerical results

SVD noise

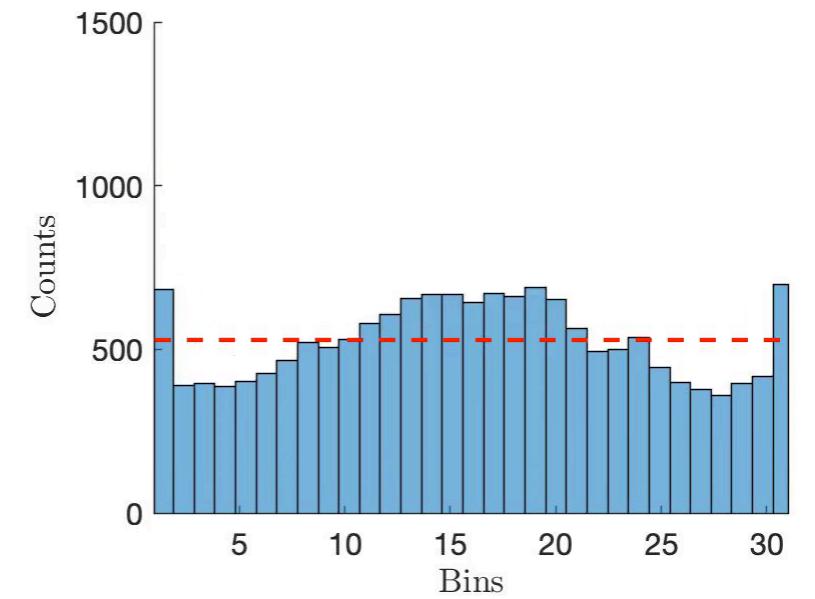
Euler Maruyama



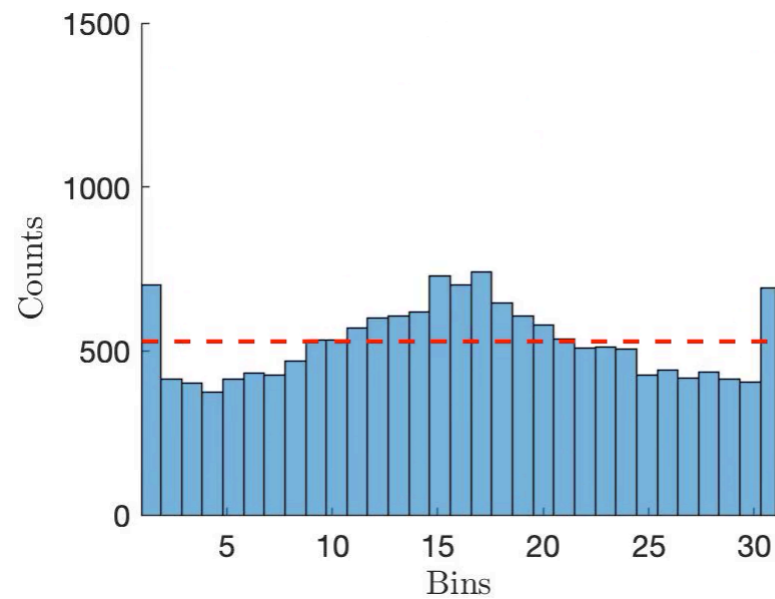
Milstein weak



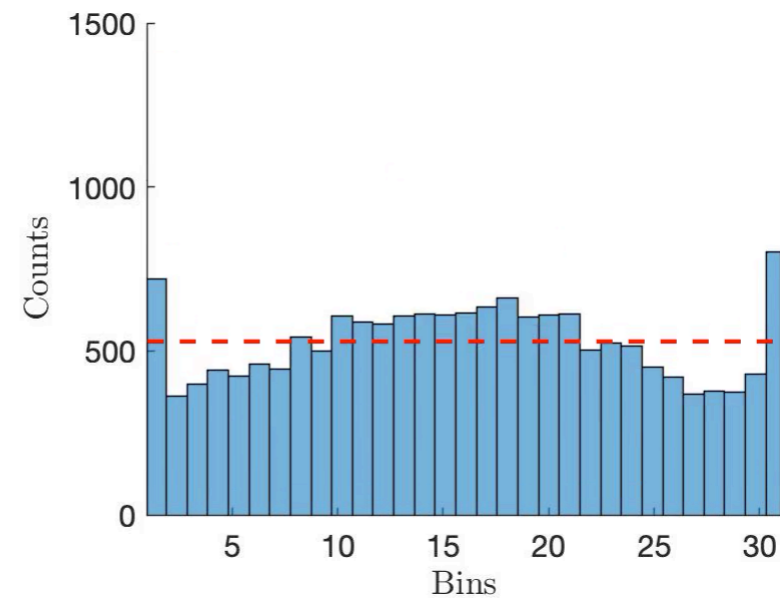
Milstein 0



Conditional 3



Conditional 4



Is $G^{m,k}$ symmetric after all?

We recall the following definition:

$$G^{m,k} = \nabla \cdot (\varphi_m \varphi_k^T \nabla b)$$

And introduce the following matrices:

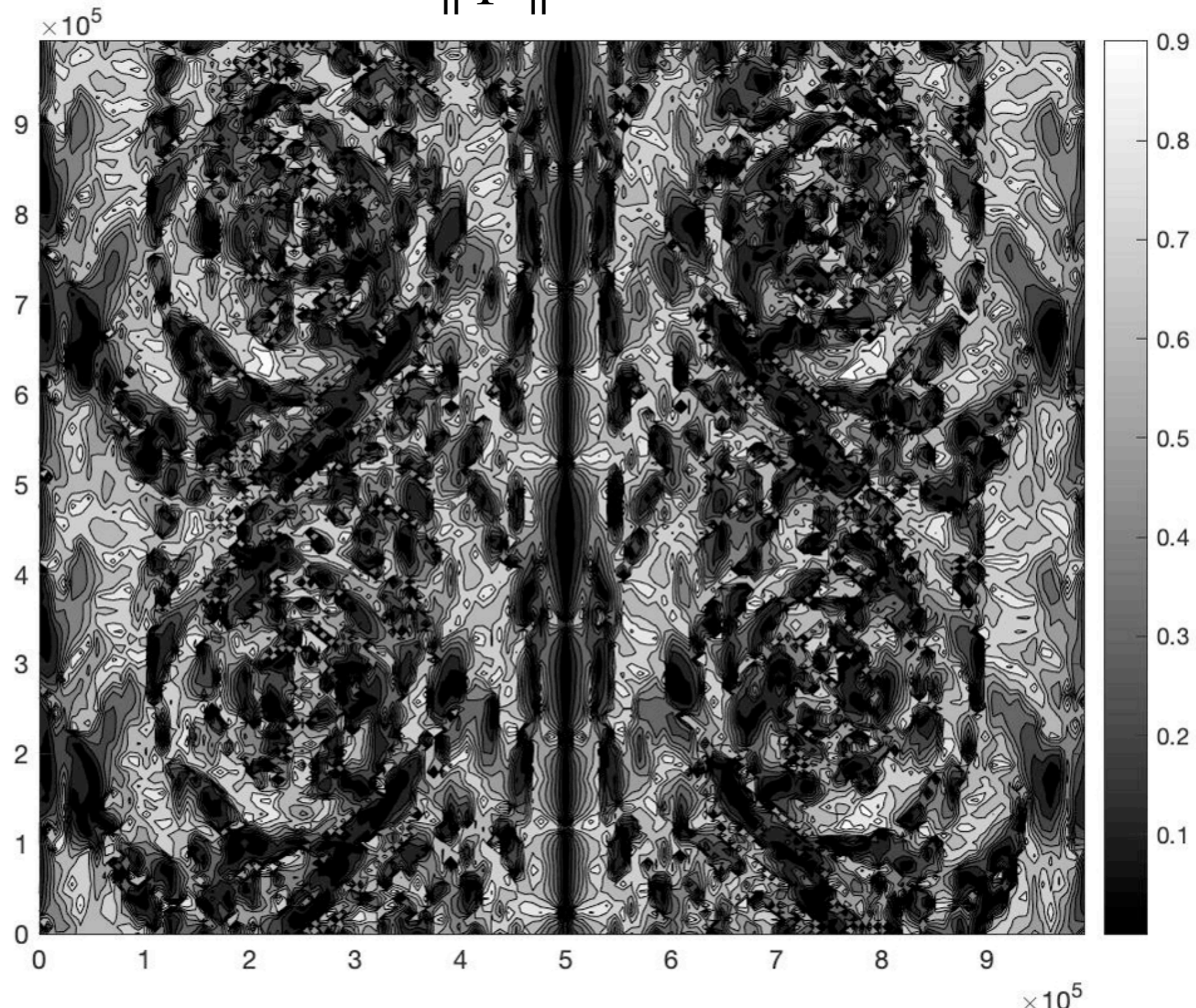
$$\Phi^{m,k} := \varphi_m \varphi_k^T$$

The symmetric and antisymmetric parts are:

$$\Phi^A = \frac{\Phi^{m,k} - \Phi^{k,m}}{2}$$

$$\Phi^S = \frac{\Phi^{m,k} + \Phi^{k,m}}{2}$$

$$\frac{\|\Phi^A\|}{\|\Phi^S\|} \quad \forall m, k \quad \text{for the POD noise}$$



Conclusion and perspectives

Conclusion

- Milstein schemes improve significantly the numerical results;
- The Lévy area does not seem to play a key role in these test cases.

Perspectives

- Understand if the (non) importance of the Lévy area is related to the test case, the equations, or other factors
- Apply this numerical scheme to other equations, starting with barotropic QG.